

IIIème Cycle Romand de Mathématiques

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Geometric Measure Theory: Old and New

Some applications of Geometric Measure Theory

<http://igat.epfl.ch/diablerets05/>

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Some applications of GMT

There are many applications of GMT.
I chose few one close to PDEs and
the Calculus of Variations

- I
Lecture { BV functions (quick survey)
SBV functions and Ambrosio's compactness theorem
- II { Approximation of minimal perimeters by
scalar Cingburg-Landau functionals } Γ -convergence
- III
&
IV { Coarea formula, oriented coarea formula
Jacobian (of Lipschitz maps)
Distributional Jacobian (of Sobolev maps)
Some applications / essential singularities } Currents
are needed
here!

FIRST LECTURE

1

Why BV functions....

GENERAL OBSERVATION:

$$u \text{ minimizes } F(u) := \int_{\Omega} f(x, u, \nabla u) \, dx$$

with Dirichlet boundary condition $u=g$ on $\partial\Omega$

↓ (and ↑ if F is convex)

u solves the PDE: $\operatorname{div} \left(\frac{\partial f}{\partial p}(x, u, \nabla u) \right) = \frac{\partial f}{\partial u}(x, u, \nabla u)$ E.L. eq. of F

with the Dirichlet bdy cond. $u=g$ on $\partial\Omega$

Example: u minimizes $F(u) := \int_{\Omega} \frac{1}{2} |\nabla u|^2 + fu$ with $u=g$ on $\partial\Omega$

$$u \text{ solves } \begin{cases} \Delta u = f & \text{on } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

DIRECT METHODS IN CALC. VAR.

Prove the existence of minimizers of F
Semicontinuity and compactness arguments
(and deduce the existence of solutions
for the Euler-Lagrange eq. associated
to F).

Dirichlet (principle), Hilbert, Tonelli.

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In other words, we want to argue as follows:

Let F be a lower semicontinuous function (a.l.)
on a topological space X , and assume that the
sublevels of F (the sets $\{u \in X : F(u) \leq C\}$)
are sequentially (pre)compact.

Then every minimizing sequence (u_n)
(that is (u_n) satisfies $F(u_n) \rightarrow \inf_{u \in X} F(u)$)

admits a converging subsequence (u_{n_k})
and the limit is a minimizer of F .

Example

$$F(u) := \int_{\Omega} \frac{1}{2} |\nabla u|^2 + fu \quad \text{is lower semicontinuous}$$

$$\text{on } X := \{u \in W^{1,2}(\Omega) : u=g \text{ on } \partial\Omega\}$$

w.r.t. the weak topology.

Sublevels of F are bounded and weak-closed
in $W^{1,2}$, and therefore sequentially compact

We need to use Sobolev spaces such
as $W^{1,2}$!

Question:

What about $F(u) := \int_{\Omega} \sqrt{1 + |\nabla u|^2}$?
area of the graph of u

BV functions

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Def.: $BV(\Omega) := \{ u \in L^1(\Omega) : \underbrace{Du}_{\substack{\uparrow \\ \text{distributional gradient}}} \text{ is a bounded } \underbrace{\text{measure}}_{\substack{\downarrow \\ \text{valued in } \mathbb{R}^n}} \}$

in other words there exists
real measures μ_i s.t.

$$\boxed{\int_{\Omega} \frac{\partial \phi}{\partial x_i} u = - \int_{\Omega} \phi d\mu_i \quad \text{for } i=1, \dots, n} \quad \phi \in C_c^1(\Omega)$$

and $Du = (\frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n}) = (\mu_1, \dots, \mu_n)$

$$\|u\|_{BV} := \|u\|_1 + \|Du\|$$

← total variation of Du
(as a vector measure)

Basic Compactness

If $\|u_n\|_{BV} \leq C < +\infty$

then there exists a subseq. (u_{n_k}) converging to $u \in BV$ in the following sense:

$$\begin{cases} u_n \rightarrow u \text{ in } L^1(\Omega) \\ Du_n \rightarrow Du \text{ in the weak* topology of measures} \end{cases}$$

(This is called weak (weak*) convergence in BV)

PROOF:

Useful tools

(Ω bounded regular domain) 4

- $BV(\Omega) \hookrightarrow L^p(\Omega)$ for every $p \leq \frac{n}{n-1}$
(the immersion is compact for $p < \frac{n}{n-1}$)

- $T : BV(\Omega) \rightarrow L^1(\partial\Omega)$ Trace operator
($T : u \mapsto u|_{\partial\Omega}$)

- $\|u - \bar{u}\|_p \leq C_{p,n} \|Du\| \quad \forall p \leq \frac{n}{n-1}$
Poincaré inequality
average of u on Ω

- $\|Du\| + |\bar{u}|$
 $\|Du\| + \|Tu\|_{L^1(\partial\Omega)}$
⋮
} are equivalent to the standard norm of BV

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Set of finite perimeter

Def. $E \subset \Omega$ has finite perimeter in Ω if $\mathbb{1}_E \in BV(\Omega)$ and we set $Per_\Omega(E) := \|D\mathbb{1}_E\|$

Motivation: if ∂E is of class C^1 , or even Lipschitz it is easy to see that

$$\mathbb{1}_E \in BV(\Omega) \text{ and } D\mathbb{1}_E = \nu_{\partial E} \cdot \mathcal{H}^{n-1} \llcorner \partial E \cap \Omega$$

Hence

$$Per_\Omega(E) := \|D\mathbb{1}_E\| = \mathcal{H}^{n-1}(\partial E \cap \Omega)$$

inner normal \uparrow
boundary in Ω \uparrow
 $(n-1)$ -dimensional Hausdorff measure

Basic Compactness (and semi-continuity)

E_n seq. of finite perimeter sets in Ω

If $Per_\Omega(E_n) \leq C < +\infty$

Then E_n converge up to subseq. to E in the L^1 sense ($\mathbb{1}_{E_n} \rightarrow \mathbb{1}_E$ in $L^1 \Leftrightarrow \mathcal{E}^1(E_n, \Delta E) \rightarrow 0$)

Moreover $Per_\Omega(E) \leq \liminf_n Per_\Omega(E_n)$

Corollary: existence of sets with minimal perimeter....

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Fine structure of BV functions

$u \in BV(\Omega)$ is approximately differentiable (in the L^1 -sense) at \mathcal{L}^n -a.e. $x \in \Omega$

there exists $\nabla u(x)$ s.t.

$$\lim_{r \rightarrow 0} \int_{|h| \leq r} \frac{|u(x+h) - u(x) - \nabla u(x) \cdot h|}{|h|} d\mathcal{L}^n(h) = 0$$

u admits an approximate limit (in the L^1 -sense) $\tilde{u}(x)$ at every x except a singular set S_u which is \mathcal{H}^{n-1} \mathcal{E} -finite

S_u is rectifiable, (countably $(\mathcal{H}^{n-1}, n-1)$ -rectifiable) that is, it can be covered by countably many C^1 -hypersurfaces (except an \mathcal{H}^{n-1} negligible subset).

In particular S_u admits a normal ν_{S_u}

For \mathcal{H}^{n-1} a.e. $x \in S_u$, there exists the approximate limits $u^+(x)$ and $u^-(x)$ on the two sides of S_u

$$Du = \underbrace{\nabla u \cdot \mathcal{L}^n}_{\text{a.c. part of } Du} + \underbrace{(u^+ - u^-) \nu_{S_u} \cdot \mathcal{H}^{n-1} \llcorner S_u}_{\text{"Jump" part of } Du} + \underbrace{D_c u}_{\text{"Cantor" part}}$$

($D\mathbb{1}_E = \nu_{\partial^* E} \cdot \mathcal{H}^{n-1} \llcorner \partial^* E$)

SBV functions

$$Du = \nabla u \cdot \mathcal{L}_n + (u^+ - u^-) \nu_{S_u} \cdot \mathcal{H}^{n-1} \llcorner S_u$$

Def. $SBV(\Omega) := \{ u \in BV(\Omega) : D_c u = 0 \}$

SBV compactness (L. Ambrosio)

Let (u_n) be a sequence in $SBV(\Omega)$ s.t.:

- $\|u_n\|_{BV} \leq C < +\infty$
- ∇u_n are equiintegrable
(i.e. $\int f(|\nabla u_n|) \leq C < +\infty$ for some $f: \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that $\frac{f(t)}{t} \rightarrow +\infty$ as $t \rightarrow +\infty$)
- $\mathcal{H}^{n-1}(S_{u_n}) \leq C < +\infty$.

Then u_n converge, up to subseq., to some $u \in SBV$.

Moreover

- $\nabla u_n \rightarrow \nabla u$ weakly in L^1
- $(Du_n)_s \rightarrow (Du)_s$ in the sense of measures

$$(u_n^+ - u_n^-) \nu_{S_{u_n}} \cdot \mathcal{H}^{n-1} \llcorner S_{u_n}$$

Application: existence of minimizers for the Mumford-Shah functional

$$F(u) := \int_{\Omega \setminus S_u} |\nabla u|^2 + \alpha \mathcal{H}^{n-1}(S_u) + \beta \int_{\Omega} |u - g|^2$$

where $g: \Omega \rightarrow [0,1]$ is given

and u is assumed e^1 out of a closed singular set S_u which is \mathcal{H}^{n-1} finite

↑ not prescribed!

arising in image segmentation problems

(but similar functionals appears in other problems....)

Direct proof in dimension $n=2$

[Mumford-Shah, Dal Maso-Morel-Solimini]

Proof by direct methods + regularity theory

EXISTENCE OF MINIMIZERS } L. Ambrosio
IN $SBV(\Omega)$

Regularity theory: minimizers } De Giorgi-
are e^1 outside a closed } -Carriero-Leaci
singular set S_u

Proof of Ambrosio's theorem

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for $n=1$ is trivial

u_n converge (up to subseq.) to some $u \in BV$

$$Du_n = \nabla u_n \cdot \mathcal{L}^1 + \sum_{i=1}^N \alpha_i \delta_{X_i} \quad \begin{array}{l} N \text{ independent} \\ \text{of } n! \end{array}$$

$$\begin{array}{ccc} \downarrow \mathcal{M}\text{-}w^* & \downarrow L\text{-}w & \downarrow \mathcal{M}\text{-}w^* \\ Du & g \cdot \mathcal{L}^1 + \sum_{i=1}^N \alpha_i \delta_{X_i} \end{array}$$

Hence $u \in SBV$, $g = \nabla u$, (and $\nabla u_n \rightarrow \nabla u$).

Not as simple in dimension $n > 1$!

Lemma (Chain rule).

If $u \in BV(\Omega)$, $\varphi: \mathbb{R} \rightarrow \mathbb{R}$ is C^1 and Lipschitz then $\varphi(u) \in BV$ [easy....]

and

$$D(\varphi(u)) = \varphi'(u) (\nabla u \cdot \mathcal{L}^n + D_c u) + (\varphi(u^+) - \varphi(u^-)) \nu_{S_u} \cdot \mathcal{H}^{n-1} \llcorner S_u$$

Characterization of SBV

Given $u \in BV$, then

$$u \in SBV \iff \exists g \in L^1 \text{ s.t. } \sup_{0 \leq \varphi \leq 1} \|D(\varphi(u)) - \varphi'(u) g \cdot \mathcal{L}^n\| < +\infty$$

And if so, $g = \nabla u$.

Proof:

Lemma (the theorem follows...)

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Let (u_n) be bounded in BV , $u_n \in SBV$ and

$u_n \rightarrow u \in BV$;

Assume $\nabla u_n \rightarrow g$ weakly in L^1 ;

Assume $\mathcal{H}^{n-1}(S_{u_n}) \leq C < +\infty$.

Then $u \in SBV$ and $g = \nabla u$.

Proof

It suffices to show that

$$\|D(\varphi(u)) - \varphi'(u) g \cdot \mathcal{L}^n\| \text{ is bounded for all } 0 \leq \varphi \leq 1$$

$$\begin{array}{ccc} \uparrow & & \uparrow \\ D(\varphi(u_n)) & & \varphi'(u_n) \cdot \nabla u_n \cdot \mathcal{L}^n \end{array}$$

Hence

$$\begin{aligned} & \|D(\varphi(u)) - \varphi'(u) g \cdot \mathcal{L}^n\| \\ & \leq \liminf \|D(\varphi(u_n)) - \varphi'(u_n) \nabla u_n \cdot \mathcal{L}^n\| \\ & \leq \liminf \|(\varphi(u_n^+) - \varphi(u_n^-)) \nu_{S_{u_n}} \cdot \mathcal{H}^{n-1} \llcorner S_{u_n}\| \\ & \leq \liminf \mathcal{H}^{n-1}(S_{u_n}) \\ & \leq C < +\infty. \end{aligned}$$

SECOND LECTURE

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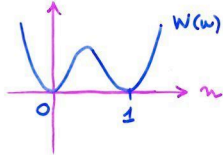
Approximation of perimeter
by scalar Ginzburg-Landau functionals

[Problem : asymptotic behaviour as $\epsilon \rightarrow 0$
of minimizers of

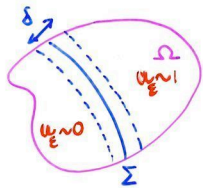
$$F_\epsilon(u) := \int_\Omega |\nabla u|^2 + \frac{1}{\epsilon^2} W(u)$$

Scalar G.L. functionals (e.g. Cahn-Hilliard) appears in phase separation models....

with prescribed average $\int_\Omega u = m, 0 < m < 1$



Heuristic



Assume u_ϵ is as in the picture. Then

$$F_\epsilon(u_\epsilon) \sim \epsilon^{n-1}(\Sigma) \mathcal{S} \left(\frac{1}{\delta^2} + \frac{1}{\epsilon^2} \right)$$

$$\sim \frac{1}{\epsilon} \mathcal{H}^{n-1}(\Sigma)$$

optimization of \mathcal{S} gives $\delta \sim \epsilon$

We expect $u \approx 1$ or 0 everywhere outside an ϵ -neighbourhood of a minimal surface Σ

(chosen among those that separate Ω into a region of volume $m|\Omega|$ and one of vol. $(1-m)|\Omega|$)

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you can do better....

Ansatz: $u_\epsilon(x) := \gamma \left(\frac{\text{dist}_\Sigma(x)}{\epsilon} \right) \quad \gamma: \mathbb{R} \rightarrow [0,1]$

Then: $F_\epsilon(u) \approx \frac{1}{\epsilon} \mathcal{H}^{n-1}(\Sigma) \int_{-\infty}^{\infty} \dot{\gamma}^2 + W(\gamma)$

after optimization of $\gamma \approx \frac{1}{\epsilon} \mathcal{H}^{n-1}(\Sigma) \text{ where } \mathcal{C} := 2 \int_0^1 \sqrt{W(u)}$

Can we make such statements rigorous?
(possibly without working too hard)

Γ -convergence (in one slide...)

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X metric space (later: a space of functions)

$$F_\varepsilon : X \rightarrow [0, +\infty]$$

Def. We say that F_ε Γ -converge to F on X if:

$$(i) \quad \forall u \in X \quad \forall u_\varepsilon \rightarrow u \quad F(u) \leq \liminf_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon)$$

$$(ii) \quad \forall u \in X \quad \exists u_\varepsilon \rightarrow u \quad F(u) = \lim_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon)$$

Definition due to DeGiorgi-Franzoni (on topological spaces)

It is actually KURATOWSKI convergence of the epigraphs $E_\varepsilon := \{(u, t) \in X \times [0, +\infty] : F_\varepsilon(u) \leq t\}$

Main property:

If u_ε minimizes F_ε on X , then every limit point u of (u_ε) is a minimizer of F

Also:

If $F_\varepsilon \xrightarrow{\Gamma} F$ and $G : X \rightarrow [0, +\infty]$ is continuous then $F_\varepsilon + G \xrightarrow{\Gamma} F + G$ (stability under cont. perturbations)

[FINDING THE Γ -LIMIT OF F_ε GIVES INFO ABOUT THE LIMIT OF MINIMIZ. u_ε]

Provided that:

(a) F is not constant !

(b) (u_ε) is pre-compact in X !

Back to the original problem

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Theorem (Modica-Mortola (77), Modica (87))

Fix $m \in (0, 1)$, let $X := \{u \in L^1(\Omega) : \int_\Omega u = m\}$

Then

$$F_\varepsilon(u) := \begin{cases} \int_\Omega \varepsilon |\nabla u|^2 + \frac{1}{\varepsilon} W(u) & \text{for } u \in W^{1,2} \\ +\infty & \text{elsewhere in } X \end{cases}$$

$\downarrow \Gamma$

$$F(u) := \begin{cases} \sigma \|Du\| = \sigma \mathcal{H}^{n-1}(\partial u) & \text{for } u \in BV(\Omega; \{0, 1\}) \\ +\infty & \text{elsewhere in } X. \end{cases}$$

Moreover every sequence (u_ε) s.t. $F_\varepsilon(u_\varepsilon) \leq C < +\infty$ is precompact in X

Corollary

If u_ε minimizes F_ε , then u_ε converge, (up to subseq.) to $u = 1_E$ where E minimizes the perimeter among all sets in Ω with measure $m|\Omega|$.

Something better can be done

Proof

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Compactness: $F_\varepsilon(u_\varepsilon) \leq C < +\infty \Rightarrow (u_\varepsilon)$ precomp. in L^1

$$F_\varepsilon(u) = \int_\Omega \varepsilon |\nabla u|^2 + \frac{1}{\varepsilon} W(u)$$

$$\geq \int_\Omega 2\sqrt{W(u)} |\nabla u|$$

with $a^2 + b^2 \geq 2ab$
with $a := \sqrt{\varepsilon} |\nabla u|$
 $b := \sqrt{W(u)/\varepsilon}$

$$= \int_\Omega |D(H(u))| = \|D(H(u))\|$$

here $H' = 2\sqrt{W}$

Hence: $C \geq F_\varepsilon(u_\varepsilon) \geq \int_\Omega |D(H(u_\varepsilon))| = \|D(H(u_\varepsilon))\|$

$\Rightarrow H(u_\varepsilon)$ is precompact in L^1

$\Rightarrow u_\varepsilon$ is precompact in L^1

Lower bound: $u_\varepsilon \rightarrow u \Rightarrow F(u) \leq \liminf_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon)$

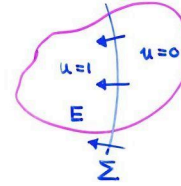
$H(u_\varepsilon) \rightarrow H(u)$ in BV weak*

Hence:

$$\begin{aligned} \liminf_{\varepsilon \rightarrow 0} F_\varepsilon(u_\varepsilon) &\geq \liminf \|D(H(u_\varepsilon))\| && \leftarrow \text{previous estimate} \\ &\geq \|D(H(u))\| \\ &= \varepsilon \mathcal{H}^{n-1}(S_u) = \varepsilon \|Du\| \end{aligned}$$

Upper bound: $\forall u \exists u_\varepsilon \rightarrow u, F_\varepsilon(u_\varepsilon) \geq F(u)$

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We can assume

$u = 1_E, E$ smooth

Let $d_\Sigma(x) :=$ oriented distance from $\partial E = \Sigma$

Set $u_\varepsilon(x) := \gamma\left(\frac{d_\Sigma(x)}{\varepsilon}\right)$

where γ solves the ODE $\begin{cases} \dot{\gamma} = 2\sqrt{W(\gamma)} \\ \gamma(0) = 1/2 \end{cases}$

Indeed for such u_ε there holds

$$\begin{aligned} F_\varepsilon(u_\varepsilon) &= \int_\Omega \varepsilon |\nabla u|^2 + \frac{1}{\varepsilon} W(u) \\ &\leq \mathcal{H}^{n-1}(\Sigma) \int_{-\infty}^{\infty} \varepsilon \dot{\gamma}^2 + \frac{1}{\varepsilon} W(\gamma) \\ &= \mathcal{H}^{n-1}(\Sigma) \int_{-\infty}^{\infty} 2\sqrt{W(\gamma)} |\dot{\gamma}| \\ &= \mathcal{H}^{n-1}(\Sigma) \int_0^1 \dot{H}(\gamma) d\gamma \\ &= \mathcal{H}^{n-1}(\Sigma) \cdot \varepsilon \end{aligned}$$

Third Lecture
JACOBIANS OF LIPSCHITZ MAPS

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Area formula

$u: \mathbb{R}^n \rightarrow \mathbb{R}^k$ Lipschitz, $n \geq k$.

Then for every $A \subset \mathbb{R}^n$

$$\int_{\mathbb{R}^k} \mathcal{H}^{n-k}(\tilde{u}(y) \cap A) dy = \int_A \rho(x) dx$$

where $\rho(x) = \sqrt{\det[(Du(x)) (Du(x))^T]}$

$k \times k$ minor of $(Du(x)) \rightarrow \sqrt{\sum_M (\det M)^2} = |du_1 \wedge \dots \wedge du_k|$
components of u

[Recall that $df = \sum \frac{\partial f}{\partial x_i} dx_i$

$= |u^\#(dy_1 \wedge \dots \wedge dy_k)|$
pull back according to u of $dy_1 \wedge \dots \wedge dy_k$, standard (volume) form on \mathbb{R}^k

Def We call k -dimensional Jacobian of $u: \mathbb{R}^n \rightarrow \mathbb{R}^k$ the k -form

$$J_u := du_1 \wedge \dots \wedge du_k = u^\#(dy_1 \wedge \dots \wedge dy_k)$$

ATTENTION: usually the word "Jacobian" is used for $|J_u|$. This notation (and definition) is not widely used!

Identification of vectors and covectors

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Def. $\star: \Lambda^k(\mathbb{R}^n) \rightarrow \Lambda_{n-k}(\mathbb{R}^n)$

$\star: dx_{\underline{i}} \mapsto \epsilon(\underline{j}, \underline{i}) e_{\underline{j}}$
multi-index (i_1, \dots, i_k) *complement to the multi-index \underline{i}*
sign of the permutation that re-order $(\underline{j}, \underline{i})$

\star is a (sort of) Hodge operator, identifying k -covectors and $(n-k)$ -vectors. Hence, if ω is a k -form, then $\star \omega$ is a $(n-k)$ -current.

ATTENTION: this is not the standard Hodge oper.

\star behaves nicely w.r.t. ∂ and d

$$\star(d\omega) = (-1)^{n-k} \partial(\star \omega)$$

Geometrically:

If $\omega = \omega_1 \wedge \omega_2 \wedge \dots \wedge \omega_k$ is a simple form then $\star \omega$ is a simple vector that spans the $(n-k)$ -space $(\ker \omega_1) \cap (\ker \omega_2) \cap \dots \cap (\ker \omega_k)$

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More on the coarea formula

If $u: \mathbb{R}^n \rightarrow \mathbb{R}^k$ Lipschitz

$$\left\{ \begin{array}{l} \text{Then } \int_{\mathbb{R}^k} \mathcal{H}^{n-k}(\tilde{u}^{-1}(y) \cap A) dy = \int_A |Ju| dx \quad \forall A \subset \mathbb{R}^n \end{array} \right.$$

Hence $\tilde{u}^{-1}(y)$ is \mathcal{H}^{n-k} -locally finite for \mathcal{H}^k -a.e. y .

Moreover $\tilde{u}^{-1}(y)$ is $(n-k)$ -rectifiable. [Fed].....

The result is non trivial even for u of class C^1 (cf. Sard's lemma).

Moreover $\tau(x) := \frac{\star Ju(x)}{|Ju(x)|}$ is a simple $(n-k)$ -vector that orients $\text{Tan}(\tilde{u}^{-1}(y), x)$ for \mathcal{H}^{n-k} -a.e. $x \in \tilde{u}^{-1}(y)$ and \mathcal{H}^k -a.e. y .

Hence we set $N_y = N_y(u) = [\tilde{u}^{-1}(y), \tau, \mathbf{1}]$
oriented level curve of u ...

In particular we have the oriented coarea form:

$$\int_{\mathbb{R}^k} N_y dy = \star Ju \mathcal{L}^n$$

What about the boundary of N_y ?

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Simple cases

if $n=k$ then

$$u: \mathbb{R}^k \rightarrow \mathbb{R}^k$$

$$Ju = (\det(\nabla u(x))) dx_1 \wedge \dots \wedge dx_k$$

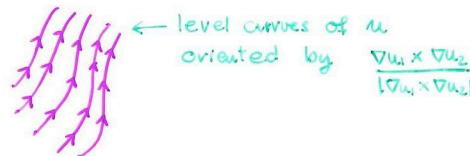
$$\star Ju = \det(\nabla u(x)) \mathcal{L}^k$$

if $n=3, k=2$ then

$$u: \mathbb{R}^3 \rightarrow \mathbb{R}^2, \quad u = (u_1, u_2)$$

$$\star Ju = \nabla u_1 \times \nabla u_2$$

vector product in \mathbb{R}^3



The oriented coarea formula says that the "diffuse" 1-current $\star Ju = (\nabla u_1 \times \nabla u_2) \mathcal{L}^3$ can be decomposed as integral of the 1-currents associated to the level curves.

if $k=1$ then

$$u: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$Ju = du = (\nabla u)^\star$$

$\frac{\nabla u}{|\nabla u|}$ orients (as a normal) the level surfaces of u

Beyond Lipschitz maps:
Jacobian of Sobolev maps

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Recall

$$W^{1,p}(\Omega; \mathbb{R}^k) := \left\{ u \in L^p(\Omega; \mathbb{R}^k) : Du \in L^p(\Omega; \mathbb{R}^{k \times n}) \right\}$$

↑
distributional derivative

Question: for which p can we define the jacobian of $W^{1,p}$ maps?

Answer: everything is fine for $p \geq k$

$$J : W^{1,p}(\Omega; \mathbb{R}^k) \rightarrow L^{p/k}(\Omega; \wedge^k(\mathbb{R}^n))$$

$$u \mapsto Ju$$

is a continuous operator

But there holds more: J is sequentially continuous from $W^{1,p}$ -weak to $L^{p/k}$ -weak (for $p > k$)

Important, and non obvious!

What about $W^{1,p}$ with $p < k$?

Fundamental identity

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for u of class C^2

$$Ju = du_1 \wedge \dots \wedge du_k = \frac{1}{k} d \left(\sum_{i=1}^k (-1)^{i-1} u_i \wedge_{j \neq i} du_j \right)$$

that is to say

Very "popular,"
in the case
 $n=k$

$$du = u^\# (dy_1 \wedge \dots \wedge dy_k) = \frac{1}{k} d \left(u^\# \left(\sum_{i=1}^k (-1)^{i-1} y_i \wedge_{j \neq i} dy_j \right) \right)$$

n-1 form called: ju

standard volume form on \mathbb{R}^k

(k-1) form on \mathbb{R}^k

||
standard volume form on every sphere centered at 0.

COROLLARY: $\star Ju$ is a boundary (precisely $\star Ju = (-1)^{n-k+1} \partial(\star ju)$)

DEFINITION (Ball, Brezis-Caron-Lieb, JERRARD-SONER)

distributional jacobian!

For every u in $W^{1,k-1}(\Omega; \mathbb{R}^k)$ we set

$$Ju := \frac{1}{k} d \left(\sum_{i=1}^k (-1)^{i-1} u_i \wedge_{j \neq i} du_j \right)$$

J is (sequentially) continuous from $W^{1,k-1} \cap L^\infty$ in $\mathcal{D}'(\Omega; \wedge^k(\mathbb{R}^n))$

More precisely, if

- u_n are uniformly bounded and
- $u_n \rightarrow u$ weakly in $W^{1,p}$ for some $p > k-1$
- strongly in $W^{1,k-1}$

then

$Ju_n \rightarrow Ju$ in the sense of distributions

$\star Ju_n \rightarrow \star Ju$ in the sense of currents

Remark: If the pointwise and the distributional jacobian are both defined ($u \in W^{1,k} \cap L^\infty$) then they agree.

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Jacobian and the area formula for Sobolev maps

Let $u \in W^{1,k}(\Omega; \mathbb{R}^k)$

Let \mathcal{D}_u be the set of approximate differentiability. Then

$$\int_{\mathbb{R}^k} \mathcal{H}^{n-k}(\tilde{u}^1(y) \cap \mathcal{D}_u) dy = \int_{\mathbb{R}^n} |Ju(x)| dx \leq \int_{\mathbb{R}^n} |Du|^k < +\infty$$

Moreover $\tilde{u}^1(y) \cap \mathcal{D}_u$ is rectifiable and oriented by $\frac{*Ju}{|Ju|} =: \tau$ for a.e. y.

given a $k \times k$ matrix $M = (m_1, \dots, m_k)$
 $|m_1 \wedge \dots \wedge m_k| \leq |M|^k$

Thus $N_y := [\tilde{u}^1(y) \cap \mathcal{D}_u; \tau; 1]$ is a rectified current and

$$\int_{\mathbb{R}^k} N_y dy = *Ju$$

Proof: \mathcal{D}_u can be covered by sets where u agrees with a Lipschitz map (countably many...)

Question: DO WE HAVE TO THROW AWAY \mathcal{D}_u ?

See: Maly-Swanson-Ziemer

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JACOBIAN OF MAPS VALUED IN SPHERES

from now on we assume $u: \Omega \subset \mathbb{R}^n \rightarrow S^{k-1} \subset \mathbb{R}^k$

If $u \in W^{1,k}(\Omega; S^{k-1})$ then $Ju = 0$

for a.e. x, du_1, \dots, du_k are linearly dependent because $du: \mathbb{R}^n \rightarrow \text{Tan}(S^{k-1}, u(x))$ and the latter has dimension $< k$.

This may not be true if $u \in W^{1,p}$ with $k \leq p < k$

Fundamental example:

$$u: \mathbb{R}^k \rightarrow S^{k-1}; \quad u(x) := \frac{x}{|x|} \quad (\text{then } u \in W^{1,p} \forall p < k)$$

then $*Ju := \alpha_k \delta_0$ ← Dirac mass at 0.
↑
volume of unit ball in \mathbb{R}^k .

Proof

$$\text{Approximate } u \text{ by } u_\epsilon := \begin{cases} \frac{x}{\epsilon} & \text{if } |x| < \epsilon \\ \frac{x}{|x|} & \text{if } |x| \geq \epsilon \end{cases}$$

$$\text{Then } *Ju_\epsilon(x) = \frac{1}{\epsilon^k} \mathbb{1}_{B(0,\epsilon)}$$

and $*Ju_\epsilon \rightarrow *Ju$ in the sense of currents...

Important

$Ju \neq du_1 \wedge \dots \wedge du_k$!
distributional definition pointwise definition
= 0 in this case

(25)

Jacobian of maps with "nice" singularities
CASE $n=k$

Given $u: \mathbb{R}^k \rightarrow S^{k-1}$ smooth outside a finite singular set $S = \{x_i\}$, then

$$\star J u = \alpha_k \sum_i d_i \delta_{x_i}$$

$$d_i := \deg(u, \partial B_i, S^{k-1})$$

where B_i is a ball that contains x_i only... it does not matter which ball!

Proof: Of course, $\star J u$ is supported in $S = \{x_i\}$!

Let ρ be a smooth radial function centered at some x_i , null on the others

$$\begin{aligned}
\int_{\mathbb{R}^k} \star J u \rho \, dx &= \int_{\mathbb{R}^k} (\rho J u) \cdot e_1 \wedge \dots \wedge e_k \\
&= \int_{\mathbb{R}^k} -d\rho \wedge \frac{1}{k} J u \\
&= \int_0^\infty -\dot{\rho}(t) \left(\int_{\partial S^{k-1}} \frac{1}{k} J u \right) dt \quad \leftarrow \text{acting on } \Sigma \text{ tangent to } \partial S^{k-1} \\
&= \int_0^\infty -\dot{\rho}(t) \frac{1}{k} d_i \operatorname{vol}(S^{k-1}) dt \quad \leftarrow \text{sphere centered at } x_i \text{ with radius } t \\
&= \rho(0) d_i \omega_k
\end{aligned}$$

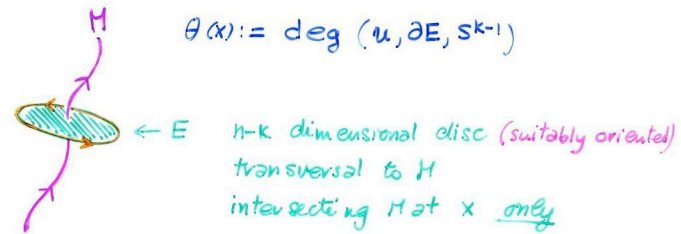
(26)

Jacobian of maps with nice singularities
CASE $m > k$

Given $u: \mathbb{R}^n \rightarrow S^{k-1}$ smooth outside an ORIENTED manifold M without boundary and with codimension k in \mathbb{R}^n then

$$\star J u = \alpha_k [M, \varepsilon_M, \theta]$$

where the multiplicity $\theta(x)$ at $x \in M$ is given by



θ is locally constant (cf. $\star J u$ has no bdy).

No proof will be given for this formula.... (it follows from the case $n=k$ by slicing techniques).

COMMENT

We might say that $\star J u$ captures the "essential" singularity of u !

$\star J u$ is sometimes called "topological singularity" of u [Riviere, Pakzad, ...]

What can be said about Jacobians of generic Sobolev maps?

THEOR. Let $u \in W^{k,k-1}(\Omega; S^{k-1})$

o Then

$$\star J u = \alpha_k \partial N$$

where N is an $(n-k+1)$ -rectifiable current with integer multiplicity.

o More precisely

$$\star J u = (-1)^{n-k+1} \alpha_k \partial N_y \quad \text{for a.e. } y \in S^{k-1}$$

COROLLARY

- o If $\star J u$ is a measure, *i.e. has finite mass!* it is also an $(n-k)$ -dimensional integral current (up to α_k)
- o In particular, for $n=k$ $\star J u$ is a finite sum of Dirac Masses!

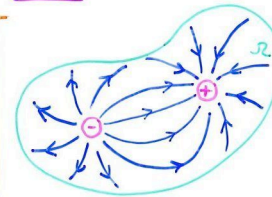
Brezis-Coron-Lieb for $n=k$

Jerrard-Soner for $n < k$

simple proof: GA.-Baldo-Orlandi (see also Hang-Lin)

Proof

PROOF BY PICTURE!



→ level curves of $u: \Omega \rightarrow S^1$

o singularities of u (where $J u$ is sitting)

Can we turn this picture into a real proof?

Since $J u := \frac{1}{k} d(ju) = \frac{1}{k} d(u^* \tilde{\omega}) \quad \left| \quad \sum_{i,j} (-1)^{i+j} y_i dy_j$

Then $\star J u = \frac{(-1)^{n-k+1}}{k} \partial(\star J u) = \frac{(-1)^{n-k+1}}{k} \int_{y \in S^{k-1}} \partial N_y d\mathcal{H}^{k-1}(y)$

This is not enough.

TO BE PROVED LATER!

We claim indeed that more holds: given $\rho: S^{k-1} \rightarrow \mathbb{R}$ such that $\int \rho = 1$ then

$$J u = \frac{1}{k} d(ju) = \frac{1}{k} d(u^* \tilde{\omega}) = \frac{1}{k} d(u^* (\rho \tilde{\omega}))$$

Hence

$$\star J u = \frac{(-1)^{n-k+1}}{k} \int_{y \in S^{k-1}} \rho(y) \partial N_y d\mathcal{H}^{k-1}(y)$$

and taking a sequence $\rho \rightarrow k \alpha_k \delta_{\bar{y}}$

$$\star J u = \frac{(-1)^{n-k+1}}{k} k \alpha_k \partial N_{\bar{y}} = (-1)^{n-k+1} \alpha_k \partial N_{\bar{y}}$$

It remains to prove the claim

$$d(u^\# \tilde{\omega}) = d(u^\#(p\tilde{\omega}))$$

where $\tilde{\omega}$ is the standard volume form on S^{k-1} , and p is a function on S^{k-1} s.t. $\int_{S^{k-1}} p = 1$, and $u \in W^{1,k-1}(\Omega, S^{k-1})$

That is, we must show that the following form is null:

$$\begin{aligned} d(u^\# \tilde{\omega}) - d(u^\#(p\tilde{\omega})) &= d(u^\# \tilde{\omega} - u^\#(p\tilde{\omega})) \\ &= d(u^\#((1-p)\tilde{\omega})) \end{aligned}$$

< But $(1-p)\tilde{\omega}$ is exact, that is $\frac{(1-p)\tilde{\omega} = d\alpha}{\text{ON } S^{k-1}}$ >

$$\begin{aligned} &= d(u^\#(d\alpha)) \\ &= d(d(u^\#\alpha)) \\ &= 0 \end{aligned}$$

Follows by the fact that $(k-1)$ -th cohomology group of S^{k-1} (and of any connected $(k-1)$ -dim manifold) is \mathbb{R} , and the identification is given by the integral....

ALTERNATIVE (FALSE!) PROOF:

$$d(u^\#((1-p)\tilde{\omega})) = u^\#(d((1-p)\tilde{\omega})) = u^\#(0) = 0$$

Why is it false?

FIRST IDENTITY REQUIRES $u \in W^{1,k}$!

the differential of a $(k-1)$ -form on any $(k-1)$ -dimensional manifold must be 0.

(FEW) APPLICATIONS

Lifting Sobolev maps

Let $u: \Omega \subset \mathbb{R}^n \rightarrow S^1$, $u \in W^{1,p}$ ($p \geq 1$)
Is there $\theta: \Omega \rightarrow \mathbb{R}$, $\theta \in W^{1,p}$
such that

$$e^{2\pi i \theta} = u \quad ?$$

This is known as "lifting problem", see Demailly, Bourgain-Brezis-Mironescu, others...

Solving this problem implies a solution of the approximation problem:
Let $u: \Omega \rightarrow S^1$, $u \in W^{1,p}$
Is there $u_n: \Omega \rightarrow S^1$, u_n of class C^1 (or C^∞)
s.t. $u_n \rightarrow u$ in norm?

In other words: is $W^{1,p}$ the completion of regular maps?

Answer:

If u can be lifted, then $Ju = 0$.

The converse is true when Ω is simply connected.

In particular there is always lifting (and approximation) for $p \geq 2$.

The case $p < k$ would have been trivial.

THE PROOF IS SIMPLE, AND WILL BE GIVEN....

Preliminary observation

Every $u \in W^{1,p}(\Omega, S^1)$ can be written

as $u = e^{2\pi i \theta}$

with $\theta \in W^{1,p}(\Omega, \mathbb{R}/\mathbb{Z})$ ← [Nothing deep: we have just changed the representation of S^1 .]

More precisely

$2\pi d\theta = u_1 du_2 - u_2 du_1 = -i \bar{u} du$ (complex form)

and since $|u|=1$

$2\pi |\nabla \theta| = |\nabla u|$

Moreover $2\pi d\theta = ju$ hence $\pi d(d\theta) = Ju$

PROOF OF THE THEOREM.

If $u = e^{2\pi i \theta}$ with $\theta \in W^{1,p}(\Omega, \mathbb{R})$

Then $Ju = \pi d(d\theta) = 0$.

is not 0 because θ is NOT a zero-form (it is not valued in \mathbb{R})

On the other hand, $Ju = 0$ implies that the 1-form $d\theta$ is exact, that is $d\theta = d\tilde{\theta}$ for some \mathbb{R} -valued $\tilde{\theta}$.

Up to some constant, $\tilde{\theta}$ provides the lifting of u .

Remarks

The problem of Lifting has been studied by Bourgain, Brezis, Mironescu in particular for maps in fractional Sobolev spaces of maps from $\Omega \rightarrow S^1$

Note: the Jacobian can be defined even for $u \in H^{1/2}(\Omega, \mathbb{R}^2)$, and turns out to be the only obstruction to lifting [see: Han-Lin, Riviere, ...]

The problem of approximation for maps $u \in W^{1,p}(B, M)$ has been studied by Bethuel

↑ unit ball in \mathbb{R}^n ← k-dimensional manifold

(characterization of all p, M such that approx. exists).

Further studies by many others (Brezis-Li, Lin, ...)

For $u \in W^{1,p}(B^k, S^{k-1})$, $k-1 < p < k$, the Jacobian is the obstruction to approximation...

Example: $W^{1,p}(B^k, S^{k-1})$:

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ONE FINAL QUESTION

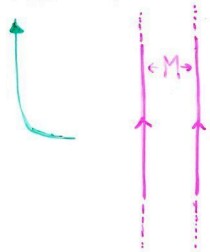
Given M $(n-k)$ -dimensional manifold without boundary in \mathbb{R}^n is there $u: \mathbb{R}^n \rightarrow S^{k-1}$ smooth outside M such that

$$\star Ju = \alpha_k M \quad ?$$

ANSWER [Alberti-Baldo-Orlandi]: $\alpha_k [M, \tau_M, 1]$ YES FOR $k=2$

YES (AND NO) FOR $k > 2$ ← One must allow for an additional singularity (besides M) of dimension $n-k-1$!

NO FOR $k=1$



← this 1-dimensional oriented manifold in \mathbb{R}^2 is not a boundary

Hence cannot be the Jacobian (derivative) of a map $u: \mathbb{R}^2 \rightarrow \{\pm 1\}$

Similar question: Given M $(n-k)$ -dimensional integral boundary in $\Omega \subset \mathbb{R}^n$ (or even $M = \text{bdry of integral multiplicity rectifiable current}$), is there $u \in W^{1,k-1}(\Omega, S^{k-1})$ s.t.

$$\star Ju = \alpha_k M$$

ANSWER [A-B-O]: YES FOR $k \geq 2$!

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AN INTERESTING GEOMETRIC CONSTRUCTION FOR $k=2$

Given M smooth, oriented, without boundary in \mathbb{R}^n and dimension $n-2$, we want to find $\theta \in W^{1,1}(\mathbb{R}^n, \mathbb{R}/\mathbb{Z})$ smooth outside M such that

$$(1) \quad \star d(d\theta) = [M, \tau_M, 1]$$

[The desired map u will be $u := e^{2\pi i \theta}$]

Setting $\omega := d\theta$, equation (1) becomes

$$(2) \quad \int_{\gamma} \omega \cdot \tau_{\gamma} = \text{Link}(M, \gamma)$$

for every curve γ in $\mathbb{R}^n \setminus M$

WE JUST CONSTRUCT ω SATISFYING (2). IT WILL (AUTOMATICALLY!) BE OF THE FORM $\omega = d\theta$.

By definition

$$\text{Link}(M, \gamma) = \deg(\Phi; M \times \gamma, S^{k-1}) =$$

$$= \int_{M \times \gamma} \Phi^{\#} \tilde{\omega}$$

↑ $\Phi(x,y) = \frac{x-y}{|x-y|}$
standard volume form on S^{k-1}

$$= \int_{\gamma} \left[\int_M (\Phi^{\#} \tilde{\omega})(x,y) \cdot \tau_M(x) \right] \cdot \tau_{\gamma}(y)$$

HENCE IT SUFFICES TO SET $(k-1)$ -form applied to a $(k-2)$ -vector = 1-form !

$$\omega(y) = \int_M (\Phi^{\#} \tilde{\omega})(x,y) \cdot \tau_M(x)$$

References (minimal list).

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an approach via Γ -convergence >

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see my
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DISTRIBUTIONAL JACOBIANS:

Jerrard-Soner: Functions of bounded

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G.A.-Baldo-Orlandi: Maps with

prescribed singularities [JEMS]